Advection-diffusion with sharp interfaces, coupled with a fluid

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Introduction

- Lattice Boltzmann Method (+ HPC): significant achievements in CFD → modelling complex flows (multiphase fluids, thermal and buoyancy effects...)
- Advection-diffusion (AD) = common problem to simulate transport of quantities such as temperature, concentration of species...





Lateral transport of volcanic ash in air



Rayleigh-Bénard instability N=100; Ra=1E+08; Pr=1

Introduction

- Advection-dominated problems = challenge for mesh-based schemes
- An example : transport of particles (modelled by a continuum field under some assumptions) with very low diffusivity.
- Interesting in order to avoid simulating individually very large number of particles
- If we add on top some sharp interfaces → problems related to numerical diffusion, dispersion...



Coupled system

• Case study: A settling-driven Rayleigh-Taylor problem



Coupled system

• Unstable PBL collapses → downward moving fingers



Laboratory experiments on settling-driven Raleigh-Taylor (Credits: Allan FRIES)



Coupled system - Governing equations

• How to model this ?

→ Three-way coupling between fluid, sugar and particles.

• Fluid (momentum): $\frac{\partial \vec{u}_f}{\partial t} + \left(\vec{u}_f \cdot \vec{\nabla}\right) \vec{u}_f = -\frac{1}{\rho_0} \vec{\nabla} p + \nu \nabla^2 \vec{u}_f + \left[\left(\frac{\rho_p - \rho_0}{\rho_0} \right) \mathbf{\emptyset} + \left(\frac{\rho(S)}{\rho_0} - 1 \right) (1 - \mathbf{\emptyset}) \right] \vec{g}$

• Particles :
$$\frac{\partial \emptyset}{\partial t} + \vec{\nabla} \cdot \left[\emptyset \left(\vec{u}_f - V_s(S) \vec{e}_z \right) \right] = D_c \nabla^2 \emptyset$$

• Sugar:
$$\frac{\partial \rho}{\partial t} + \vec{u}_f \cdot \vec{\nabla \rho} = D_S \nabla^2 \rho$$
 (assuming $\rho = \rho_0 (1 + \alpha S)$)

- Assumptions to model particles as a continuum:
 - Small particles and large number
 - Drag force in equilibrium with gravitational force (Boussinesq)
- Particles have very small diffusivity → Convection-dominated problem !



How to solve the advection-diffusion equations ?



- 1. LBM for the Advection-Diffusion
- Similar to Navier-Stokes equations (which can be seen as the AD of the momentum density vector $\rho \vec{u}$)
- For instance the BGK model, the relaxation time in the LB equation is given by: $\tau = \frac{D}{c_s^2} + \frac{\delta t}{2}$
- All dynamics related to AD using LBM are in palabos\src\complexDynamics\advectionDiffusionDynamics.h



- 2. <u>Upwind Finite-Difference 1st order:</u>
- Adaptive scheme which takes in account the velocity direction in order to discretize (by a Taylor expansion) the convective term

$$u \frac{\partial u}{\partial x}$$

Лa

 \circ If u > 0 we use the backward difference

$$\left(\frac{\partial a}{\partial x}\right)_{B} \approx \frac{a_{i}^{n} - a_{i-1}^{n}}{\delta x}$$

 \circ If u < 0 we use the forward difference

$$\left(\frac{\partial a}{\partial x}\right)_{F} \approx \frac{a_{i+1}^{n} - a_{i}^{n}}{\delta x}$$



3. <u>Upwind Finite-Difference 2nd order:</u>

 \circ If u > 0 we use the backward difference

$$\left(\frac{\partial a}{\partial x}\right)_{B} \approx \frac{3a_{i}^{n} - 4a_{i-1}^{n} + a_{i-2}^{n}}{2\delta x}$$

 \circ If u < 0 we use the forward difference

$$\left(\frac{\partial a}{\partial x}\right)_{F} \approx \frac{-a_{i+2}^{n} + 4a_{i+1}^{n} - 3a_{i}^{n}}{2\delta x}$$

 Note that here we need 2 neighbours, which is important when initializing the scalar field associated (envelope)

4. WENO 3rd order

- Allows to solve hyperbolic partial differential equations of the form $\frac{\partial \phi}{\partial t} + \frac{\partial h}{\partial x} = 0$ where, in our case, the flux $h(\phi) = u\phi$ (Jiang and Shu, 1996; Liu et al. 1994)
- Ensures the suppression of spurious oscillations around discontinuities. Third order accurate in smooth regions and second order near discontinuities.
- Principle: build a convex combination of interpolants for the flux at given points of the domain, using two adjacent stencils of two points each
- Discretisation of the convective term:

$$\frac{\partial h}{\partial x} = \frac{h_{i+\frac{1}{2}} - h_{i-\frac{1}{2}}}{\delta x}$$

- $h_{i+\frac{1}{2}}$ is the flux at the half node location $x_{i+\frac{1}{2}}$.
- 3 ways to approximate $h_{i+\frac{1}{2}}$:
 - $h_{i+\frac{1}{2}}^{(1)}$: interpolation with polynomials of degree 1 in Stencil 1 (second order accurate)
 - $h_{i+\frac{1}{2}}^{(2)}$: interpolation with polynomials of degree 1 in Stencil 2 (second order accurate)
 - $h_{i+\frac{1}{2}}^{(3)}$: interpolation with polynomials of degree 2 in Stencil 3 (third order accurate)





4. WENO 3rd order

• If h is smooth in the Stencil 3, we can write $h_{i+\frac{1}{2}}^{(3)}$ as a linear combination of the two second order approximations:

$$h_{i+\frac{1}{2}}^{(3)} = \gamma_1 h_{i+\frac{1}{2}}^{(1)} + \gamma_2 h_{i+\frac{1}{2}}^{(2)}$$

where $\gamma_1 = 3/4$ and $\gamma_2 = 1/4$

• What if there is a discontinuity in one of the stencils ?

The linear coefficients are replaced by « smoothness indicators » and we have:

$$h_{i+\frac{1}{2}} = \omega_1 h_{i+\frac{1}{2}}^{(1)} + \omega_2 h_{i+\frac{1}{2}}^{(2)}$$

If h is smooth in all the stencils, $\omega_i \rightarrow \gamma_i$ and ensures a third-order accuracy. Conversely, the presence of any discontinuity in the *i*-th stencil means $\omega_i \rightarrow 0$, decreasing the accuracy to second-order.



What about the time discretization ?

- For the 1st (and higher) order finite difference, we use the Euler explicit discretization for the time.
- For the WENO scheme (3rd order), to ensure a Total Variation Diminishing (TVD) property, we perform a 3rd order Runge-Kutta procedure for the time discretization.



Coupling in Palabos

- Let's model the fluid motion using the LBM. Examples of dynamics taking in account a force term available in Palabos:
 - NaiveExternalForceBGKdynamics, GuoExternalForceBGKdynamics, GuoExternalForceConsistentSmagorinskyCompleteRegularizedBGKdynamics...
- Two "levels" of coupling:
 - Introduce the fluid velocity field in the convective term of the advection-diffusion
 - Implement the buoyant force term (which depends on the particle volume fraction and the sugar concentration)



template< typename T, template<typename U1> class FluidDescriptor, template<typename U2> class VolfracDescriptor> void VelocityCouplingProcessor2D<T,FluidDescriptor,VolfracDescriptor>::process (Box2D domain BlockLattice2D<T,FluidDescriptor>& fluid, BlockLattice2D<T,VolfracDescriptor>& VolFrac) enum {velOffset = VolfracDescriptor<T>::ExternalField::velocityBeginsAt,}; Dot2D offset = computeRelativeDisplacement(fluid, VolFrac); for (plint iX=domain.x0; iX<=domain.x1; ++iX){</pre> for (plint iY=domain.v0: iV<=domain_v1. ++iv) T *u = VolFrac.get(iX+offset.x,iY+offset.y).getExternal(velOffset); Arrav(T.FluidDescriptor(1)::a> vel, vel tot; fluid.get(iX,iY).computeVelocity(vel); vel tot = vel + vseq;vel_tot.to_cArray(u);



Coupling in Palabos (Force term)

```
template< typename T, template<typename U> class FluidDescriptor >
void ForceTermProcessor2D<T,FluidDescriptor>::processGenericBlocks (
        Box2D domain, std::vector<AtomicBlock2D*> fields )
    typedef FluidDescriptor<T> D;
    enum {
        forceOffset = FluidDescriptor<T>::ExternalField::forceBeginsAt
    };
    PLB PRECONDITION(fields.size()==3);
    BlockLattice2D<T, FluidDescriptor>* fluid = dynamic cast<BlockLattice2D<T, FluidDescriptor>*>(fields[0]);
    ScalarField2D<T>* volfracfield = dynamic cast<ScalarField2D<T>*>(fields[1]);
    ScalarField2D<T>* densityfield = dynamic cast<ScalarField2D<T>*>(fields[2]);
    Dot2D offset1 = computeRelativeDisplacement(*fluid, *volfracfield);
    Dot2D offset2 = computeRelativeDisplacement(*fluid, *densityfield);
    for (plint iX=domain.x0; iX<=domain.x1; ++iX)</pre>
        for (plint iY=domain.y0; iY<=domain.y1; ++iY)</pre>
                T *force = fluid->get(iX,iY).getExternal(forceOffset);
                for (pluint iD = 0; iD < D::a; ++iD)
                       force[iD] = /* Implement the force term here */;
```

Application to problems with sharp interfaces

• Reminder for the LBM-BGK:
$$\tau = \frac{D}{c_s^2} + \frac{\delta t}{2}$$

For very low diffusivity D, the scheme tends toward the stability limit and some spurious oscillations appear in the domain.

- Godunov theorem: "Linear numerical schemes for solving partial differential equations (PDE's), having the property of not generating new extrema (monotone scheme), can be at most first-order accurate"
- The upwind 1st order = stable but significant numerical diffusion (cf. Taylor expansion, the error term is $\sim u \frac{\delta x}{2} \frac{\partial^2}{\partial x^2}$)
- The second order: less numerical diffusion but introduces dispersion around interfaces (Godunov theorem !).
- <u>The 3rd order WENO is stable, and provides reduced numerical diffusion (second-order accurate next to discontinuities)</u>. Possible to get higher order (e.g. WENO 5th order) but also higher computational cost.

Application to problems with sharp interfaces





- Advection-diffusion possible using a full LBM scheme
- Capability to get hybrid models by coupling the LBM with finite-difference schemes → more stable (at least when D<<1)
- The upwind schemes provide a stables model and are accurate for non convection-dominated problems and without sharp interfaces.
- The WENO procedure is interesting in order to model those problems, keeping the ease of implementation on uniform meshes.



Conclusions

- Particle-based approach: we don't solve any advection-diffusion equation.
- Injection of particle tracers in very large number in order to accurately follow the interface between different inviscid phases



J. Latt, D. Kontaxakis, L. Chatagny, F. Muggli, and B. Chopard, **Hybrid Lattice Boltzmann Method for the Simulation of Blending Process in Static Mixers**, *International Journal of Modern Physics C*, vol. 24, no. 12, p. 1340009, 2013



Exercises

• Exercise 1:

- Familiarize with the different Finite-difference schemes and see how they can be implemented in *Palabos.*
- Compare them in order to highlights the main differences.
- Check how the velocity coupling is implemented.
- Exercise 2:
 - More complex problem simulating our case study in 2D
 - Check the force term coupling and try to implement it:

$$\vec{F} = \left[\left(\frac{\rho_p - \rho_0}{\rho_0} \right) \emptyset + \left(\frac{\rho}{\rho_0} - 1 \right) (1 - \emptyset) \right] \vec{g}$$

• Run the simulation in order to observe the growing instability at the interface



Application to problems with sharp interfaces





THANK YOU ! QUESTIONS ?

